# ON THE REFLECTION OF SOUND WAVES FROM a PLANE wITH A MOVABLE PART IN THE FORM OF A CYLINDRICAL PISTON 

# (OB OTRAZHENII ZVUKOVYKH VOLN OT PLOSKOSTI S PODVIZHNOI CHAST'IU V VIDE TSILINDRICHESKOGO PORSHNIA) 

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This paper is concerned with the problem of the reflection of a plane sound wave from a rigid plane which has a movable part in the form of a rigid cylindrical piston. The force acting upon the piston from the side of the fluid is determined. An integro-differential equation of motion of the piston is constructed and its solution is given.

1. Assume that the plane sound wave, which has a pressure profile

$$
p=p_{0}\left(t+\frac{z}{c}\right), \quad p_{0}(t)=0 \quad \text { at } \quad t \leqslant 0
$$

encounters the plane $z=0$ at the instant $t=0$ and is reflected from it. After the reflection, in the axisymmetric case, the deformable part of the plane will move with a velocity $V_{z}=V(r, t)$, where $V(r, 0)=0$. We assume that the deformations are small, and we determine the pressure for $t>0$. In order to do this, it is necessary to solve the wave equation

$$
\begin{equation*}
\frac{\partial^{2} p}{\partial t^{2}}=c^{2} \Delta p \tag{1.1}
\end{equation*}
$$


subject to the conditions

$$
\begin{array}{rll}
\frac{\partial p}{\partial z} & =-\rho_{0} \frac{\partial U}{\partial t} & \text { at } \\
p=p_{0}(2 t) & \text { at } & z=0
\end{array}
$$

Fig. 1.

Here $c=$ const is the speed of sound in the fluid, $\rho_{0}=$ const is the density of the fluid. Let

$$
p=p_{1}(t, z)+p_{2}(r, t, z)
$$

where $p_{1}(t, z)$ is the solution corresponding to the reflection from a rigid plane [1]

$$
p_{1}(t, z)=p_{0}\left(t+\frac{z}{c}\right)+p_{0}\left(t-\frac{z}{c}\right)
$$

Then, in order to determine $p_{2}(r, t, z)$ it is necessary to solve Equation (1.1) with the conditions

$$
\begin{equation*}
\frac{\partial p_{2}}{\partial z}=-p_{0} \frac{\partial V}{\partial t} \quad \text { at } z=0, \quad \text { ' } p_{2}=0 \quad \text { at } \quad z=c t \tag{1.2}
\end{equation*}
$$

(the first condition holds at the deformable part of the plane). The solution of Equation (1.1) with the conditions (1.2) is given in the form [2]

$$
p_{2}(r, t, z)=\frac{c \rho_{0}}{2 \pi} \int_{0}^{2 \pi} d \varphi \int_{z / \mathrm{c}}^{t} V_{i}^{\prime}(\eta, t-\tau) d \tau \quad\binom{\eta=\sqrt{r^{2}+L^{2}+2 r L \cos \varphi}}{L=\sqrt{c^{2} \tau^{2}-z^{2}}}
$$

2. Let the deforming part of the plane be represented by a movable rigid piston placed into a cutout in the plane. In this case $V=V(t)$ and at the surface of the piston $z=0$

$$
p_{2}(r, \tau, 0)=\frac{c \rho_{0}}{2 \pi} \iint_{S} V^{\prime}(t-\tau) d \varphi d \tau
$$

With fixed $r$ and $t$ the limits of integration with respect to $\phi$ and $r$ are determined from the conditions of the intersection of a circle of radius $R$ ( $R$ is the radius of the piston) with a circle of radius $c t$ whose center lies at a distance $r$ from the axis of the piston (Fig. 1).

Depending on the values of $r$ and $t$ three cases are possible:
First Case. $0 \leqslant t<(R-r) / c ;$ (Fig. 1, a)

$$
p_{2}(r, t, 0)=\frac{c \rho_{0}}{2 \pi} \int_{0}^{2 \pi} d \varphi \int_{0}^{t} V^{\prime}(t-\tau) d \tau=c p_{0} V(t)
$$

The total pressure is

$$
\begin{equation*}
p(r, t, 0)=2 p_{0}(t)+c \rho_{0} V(t) \tag{2.1}
\end{equation*}
$$

Second Case. $(R-r) / c \leqslant t \leqslant(R+r) / c ;$ (Fig. 1,b)

$$
\begin{gathered}
p_{2}(r, t, 0)=\frac{c \rho_{0}}{2 \pi}\left[\int_{\varphi_{0}}^{2 \pi-\varphi_{0}} d \varphi \int_{0}^{t} V^{\prime}(t-\tau) d \tau+\int_{-\varphi_{0}}^{\varphi_{0}} d \varphi \int_{0}^{T} V^{\prime}(t-\tau) d \tau\right]= \\
=c{p_{0}} V(t)-\frac{c \rho_{0}}{\pi} \int_{0}^{\varphi_{0}} V(t-T) d \varphi
\end{gathered}
$$

The total pressure is

$$
\begin{equation*}
p(r, t, 0)=2 p_{0}(t)+c \rho_{0} V(t)-\frac{c \rho_{0}}{\pi} \int_{0}^{\varphi_{0}} V(t-T) d \varphi \tag{2.2}
\end{equation*}
$$

Third Case. $(R+r) / e<t<\infty$ (Fig. 1, c )

$$
p_{2}(r, t, 0)=\frac{c \rho_{0}}{2 \pi} \int_{0}^{2 \pi} d \varphi \int_{0}^{T} V^{\prime}(t-\tau) d \tau=c \rho_{0} V(t)-\frac{c \rho_{0}}{\pi} \int_{0}^{\pi} V(t-T) d \varphi_{0}
$$

The total pressure is

$$
\begin{equation*}
p(r, t, 0)=2 p_{0}(t)+c \rho_{0} V(t)-\frac{c \rho_{0}}{\pi} \int_{0}^{\pi} V(t-T) d \varphi \tag{2.3}
\end{equation*}
$$

Here

$$
\Phi_{0}=\cos ^{-1} \frac{R^{2}-r^{2}-c^{2} t^{2}}{2 r c t}, \quad T=\sqrt{R^{2}-r^{2} \sin ^{2} \varphi}-r \cos \varphi, \quad T\left(r, \varphi_{0}\right)=\mathrm{t}
$$

The compressive force, which acts upon the piston from the fluid side, is

$$
F(t)=\iint_{r \leqslant R} p(r, t, 0) d \sigma=2 \pi \int_{0}^{R} p(r, t, 0) r d r
$$

At $t=0$ a cylindrical wave appears near the edges of the piston, which then propagates with velocity $e$ towards the center of the piston. The wave front $r^{\circ}=R-c t$ divides the surface of the piston into two regions. For $t<R / C$ in the first region ahead of the wave front, where $0 \leqslant r<r^{\circ}, t<(A-r) / c$, the pressure is determined from the formula (2.1); in the second region behind the wave front, where $r^{\circ} \leqslant p<R$, $(R-r) / c \leqslant t \leqslant(A+r) / c$, the pressure is determined from the formula (2.2). Thus we shall have

$$
\begin{aligned}
& F(t)-2 \pi \int_{0}^{R-c t}\left[2 p_{0}(t)+c p_{0} V(t)\right] r d r+2 \pi \int_{R}^{R}\left\{2 p_{0}(t)+c p_{0} V(t)-\right. \\
& \left.-\frac{c \rho_{0}}{\pi} \int_{0}^{\varphi_{0}(r, t)} V[t-T(r, \varphi)] d \varphi\right\} r d r=\pi R^{2}\left[2 p_{0}(t)+c p_{0} V(t)\right]-2 c p_{0} \Phi_{1}
\end{aligned}
$$

$$
\Phi_{1}=\int_{R}^{R} r d r \int_{0}^{\varphi_{0}(r . t)} V[t-T(r ; \varphi)] d \varphi
$$

In order to evaluate the integral $\Phi_{1}$ we let

$$
t-T(r, \varphi)=\tau, \quad \tau(r, 0)=t-(R-r) / c, \quad \tau\left(r, \varphi_{0}\right)=0
$$

and, after interchanging the order of integration, we obtain

$$
\begin{gather*}
\Phi_{1}=\int_{0}^{t} V(\tau) d \tau \int_{R}^{R} \frac{\Psi(r) r d r}{(t-\tau) \sqrt{1-\Psi^{2}(r)}}=c R \int_{0}^{t} \sqrt{1-\left[\frac{c(t-\tau)}{2 R}\right]^{2}} V(\tau) d \tau \\
\Psi(r)=\frac{R^{2}-r^{2}+c^{2}(t-\tau)^{2}}{2 R c(t-\tau)} \tag{2.4}
\end{gather*}
$$

At the instant $t=R / c$ the wave reflects at the center and then goes to the edge; the wave front is at $r^{\circ}=c t-R$. In the time interval $R / c \leqslant t \leqslant 2 R / c$ in the first region ahead of the reflected wave iront, where $r^{\circ} \leqslant r \leqslant R, R / c \leqslant t \leqslant(A+r) / c$, the pressure is determined by Formula (2.3). In the second region behind the reflected wave front, where $0 \leqslant r \leqslant r^{0},(R+r) / c<t \leqslant 2 R / c$, the pressure is determined by Formula (2.2). As a result we obtain

$$
\begin{gathered}
F(t)=2 \pi \int_{c t-R}^{R}\left\{2 p_{0}(t)+c \rho_{0} V(t)-\frac{c \rho_{0}}{\pi} \int_{0}^{\pi} V[t-T(r, \varphi)] d \varphi\right\} r d r+ \\
+2 \pi \int_{0}^{c t-R}\left\{2 p_{0}(t)+c \rho_{0} V(t)-\frac{c \rho_{0}}{\pi} \int_{0}^{\varphi_{0}(r, t)} V[t-T(r, \varphi)] d \varphi\right\} r d r \\
=\pi R^{2}\left[2 p_{0}(t)+c p_{0} V(t)\right]-2 c \rho_{0} \Phi_{2}
\end{gathered}
$$

Here

$$
\Phi_{2}=\int_{0}^{c t-R} r d r \int_{0}^{\varphi_{0}(r, t)} V[t-T .(r, \varphi)] d \varphi+\int_{c t-R}^{R} r d r \int_{0}^{\pi} V[t-T(r, \varphi)] d \varphi=\Phi_{1}
$$

This result is obtained by calculations similar to those performed before.

For the time interval $2 R / c<t<\infty$ the pressure is determined by Formula (2.3); thus

$$
\begin{gathered}
F(t)=2 \pi \int_{0}^{R}\left\{2 p_{0}(t)+c \rho_{0} V(t)-\frac{c \rho_{0}}{\pi} \int_{0}^{\pi} V[t-T(r, \varphi)] d \varphi\right\} r d r \\
=\pi R^{2}\left[2 p_{0}(t)+c \rho_{0} V(t)\right]-2 c \rho_{0} \Phi_{3}
\end{gathered}
$$

After some calculations we have

$$
\Phi_{3}=\int_{0}^{R} r d r \int_{0}^{\pi} V[t-T(r, \varphi)] d \varphi=c R \int_{t-2 R / c}^{t} \sqrt{1-\left[\frac{c(l-\tau)}{2 R}\right]^{2}} V(\tau) d \tau
$$

Thus, for the time interval $0 \leqslant t \leqslant 2 R / c$, in which the wave that comes from the edge of the piston will reach the center and after reflection at the center will return to the edge, we have

$$
\begin{equation*}
F(t)=\pi R^{2}\left[2 p_{0}(t)+c \rho_{0} V(t)\right]-2 c^{2} \rho_{0} R \int_{0}^{t} \sqrt{1-\left[\frac{c(t-\tau)}{2 R}\right]^{2}} V(\tau) d \tau \tag{2.5}
\end{equation*}
$$

For the time interval $2 R / c<t \leqslant \infty$ we have

$$
\begin{equation*}
F(t)=\pi R^{2}\left[2 p_{0}(t)+c \rho_{0} V(t)\right]-2 c^{2} \rho_{0} R \int_{t-2 R / c}^{t} \sqrt{1-\left[\frac{c(t-\tau)}{2 R}\right]^{2}} V(\tau) d \tau \tag{2.6}
\end{equation*}
$$

3. Let us construct the equation of motion of the piston. We denote its displacement by $u(t)$, and obtain

$$
\pi R^{2} h \rho \frac{d^{2} u}{d t^{2}}=F(t)-F_{r} \quad\left(\frac{d u}{d t}=-V(t)\right)
$$

Here $\rho$ is the density, $h$ is the thickness of the piston, $F_{r}$ is the reaction force which acts upon the piston from the opposite side. Assume that

$$
F_{r}=c_{1} \frac{d u}{d t}+c_{2} u
$$

Now we shall transform to nondimensional quantities

$$
t_{1}=\frac{c t}{2 R}, \quad u_{1}=\frac{u}{2 R}, \quad p_{01}=4 \frac{R p_{0}}{h \rho c^{2}}
$$

After dropping the subscript 1 we obtain the equation of motion of the piston in the form

$$
\begin{align*}
& u^{\prime \prime}(t)+2 \alpha u^{\prime}(t)+\beta u(t)=p(t)+\varepsilon \int_{0}^{t} \sqrt{1-(t-\tau)^{2}} u^{\prime}(\tau) d \tau \quad(0 \leqslant t \leqslant 1)  \tag{3.1}\\
& u^{\prime \prime}(t)+2 \alpha u^{\prime}(t)+\beta u(t)=p(t)+\varepsilon \int_{t-1}^{t} \sqrt{1-(t-\tau)^{2}} u^{\prime}(\tau) d \tau \quad(1 \leqslant t<\infty) \tag{3.2}
\end{align*}
$$

where

$$
\begin{equation*}
\alpha=\frac{\pi}{8} \varepsilon+\frac{c_{1}}{R h \rho c}, \quad \beta=\frac{4 c_{2}}{\pi h \rho c^{2}}, \quad \varepsilon=\frac{8}{\pi} \frac{h_{\rho_{0}}}{h \rho} \tag{3.3}
\end{equation*}
$$

$$
\begin{equation*}
u(0)=0, \quad u^{\prime}(0)=0 \tag{3.4}
\end{equation*}
$$

From this we see that the motion of a cylindrical piston under the action of an incident wave is described by an integro-differential equation, which cannot be reduced to a differential equation, unlike that of the slab-like piston [1]. Note that for $1 \leqslant t<2$

$$
\int_{t=1}^{t} \sqrt{1-(t-\tau)^{2}} u^{\prime}(\tau) d \tau=\int_{1}^{t} \sqrt{1-(t-\tau)^{2}} u^{\prime}(\tau) d \tau+\int_{t-1}^{1} \sqrt{1-(t-\tau)^{2} u^{\prime}}(\tau) d \tau
$$

Here the second integral on the right-hand side is known if we find the solution for $t<1$, and in general for $n<t<n+1(n=1,2, \ldots)$

$$
\int_{t-1}^{t} \sqrt{1-(t-\tau)^{2}} u^{\prime}(\tau) d \tau=\int_{n}^{t} \sqrt{1-(t-\tau)^{2}} u^{\prime}(\tau) d \tau+\int_{t-1}^{n} \sqrt{1-(t-\tau)^{2}} u^{\prime}(\tau) d \tau
$$

where the second integral on the right-hand side is known if we find the solution for $t<n$. The solution of Equations (3.1) and (3.2) can be represented in the form

$$
\begin{gather*}
u(t)=\int_{0}^{t} p(t-\tau) q(\tau) d \tau \quad(0 \leqslant t \leqslant 1)  \tag{3.5}\\
u(t)=\int_{0}^{t-n} p(t-\tau) q(\tau) d \tau+\varepsilon \int_{0}^{t-n}\left[\int_{t-\tau-1}^{n} \sqrt{1-(t-\tau-\xi)^{2}} u^{\prime}(\xi) d \xi-\right. \\
\left.-u(n) \sqrt{1-(t-\tau-n)^{2}}\right] q(\tau) d \tau+u(n) q^{\prime}(t-n)+\left[u^{\prime}(n)+2 \alpha u(n)\right] q(t-n) \\
(n \leqslant t \leqslant n+1) \tag{3.6}
\end{gather*}
$$

where $q(t)$ is the solution of the equation

$$
\begin{equation*}
q^{\prime \prime}(t)+2 \alpha q^{\prime}(t)+\beta q(t)-\varepsilon \int_{0}^{t} \sqrt{1-(t-\tau)^{2}} q^{\prime}(\tau) d \tau=0 \quad(0 \leqslant t \leqslant 1) \tag{3.7}
\end{equation*}
$$

with the initial conditions

$$
\begin{equation*}
q(0)=0, \quad q^{\prime}(0)=1 \tag{3.8}
\end{equation*}
$$

4. Let us find the exact solution of Equation (3.7) with the conditions (3.8). If it is assumed that

$$
\int_{0}^{t} \sqrt{1-(t-\tau)^{2}} q^{\prime}(\tau) d \tau=q(t)-\int_{0}^{t} \frac{t-\tau}{\sqrt{1-(t-\tau)^{2}}} q(\tau) d \tau
$$

then Equation (3.7) can be written as follows:

$$
\begin{equation*}
q^{\prime \prime}(t)+2 \alpha q^{\prime}(t)+(\beta-\varepsilon) q(t)=-\varepsilon \int_{0}^{t} \frac{t-\tau}{\sqrt{1-(t-\tau)^{2}}} q(\tau) d \tau \tag{1.1}
\end{equation*}
$$

We shall seek a solution in the form of a series in the parameter $\epsilon$, which is determined according to (3.3), by letting

$$
\begin{equation*}
q(t)=q_{0}(t)+\varepsilon q_{1}(t)+\varepsilon^{2} q_{2}(t)+\ldots \tag{4.2}
\end{equation*}
$$

Substituting the series (4.2) into Equation (4.1), collecting terms which contain equal powers of $\epsilon$, and equating their sum to zero leads to a system of ordinary differential equations with constant coefficients:

$$
\begin{equation*}
q_{0}^{\prime \prime}(t)+2 \alpha q_{0}^{\prime}(t)+(\beta-\varepsilon) q_{0}(t)=0 \tag{4.3}
\end{equation*}
$$

$$
\begin{equation*}
q_{n}^{\prime \prime}(t)+2 \alpha q_{n}^{\prime}(t)+(\beta-\varepsilon) q_{n}(t)=-\int_{0}^{t} \frac{t-\tau}{\sqrt{1-(t-\tau)^{2}}} q_{n-1}(\tau) d \tau \quad(n=1,2, \ldots) \tag{4.4}
\end{equation*}
$$

## with the initial conditions

$$
\begin{equation*}
q_{n}(0)=0 \quad(n=0,1, \ldots), \quad q_{0}^{\prime}(0)=1, \quad q_{n}^{\prime}(0)=0 \quad(n=1,2, \ldots) \tag{4.5}
\end{equation*}
$$

These equations can be easily solved successively:

$$
\begin{equation*}
q_{0}(t)=\frac{1}{2 \omega}\left(e^{\lambda_{1} t}-e^{\lambda_{2} t}\right), \quad \lambda_{1,2}=-\alpha \pm \omega, \quad \omega=\sqrt{\alpha^{2}+\varepsilon-\beta} \tag{4.6}
\end{equation*}
$$

where $\omega$ can also be imaginary

$$
\begin{aligned}
q_{n}(t) & =-\int_{0}^{t} q_{0}(t-\tau) d \tau \int_{0}^{\tau} \frac{\tau-\xi}{\sqrt{1-(\tau-\xi)^{2}}} q_{n-1}(\xi) d \xi \\
& =-\int_{0}^{t} q_{n-1}(\xi) d \xi \int_{\xi}^{t} \frac{\tau-\xi}{\sqrt{1-(\tau-\xi)^{2}}} q_{0}(t-\tau) d \tau \\
& =-\int_{0}^{t} q_{n-1}(\xi) d \xi \int_{0}^{t-\xi} \frac{t-\xi-\tau}{\sqrt{1-(t-\xi-\tau)^{2}}} q_{0}(\tau) d \tau
\end{aligned}
$$

or

$$
\begin{equation*}
q_{n}(t)=-\int_{0}^{t} K(t-\tau) q_{n-1}(\tau) d \tau, \quad K(t)=\int_{0}^{t} \frac{t-\tau}{\sqrt{1-(t-\tau)^{2}}} q_{0}(\tau) d \tau \tag{4.7}
\end{equation*}
$$

We shall prove the convergence of the series (4.2) by utilizing obvious estimates

$$
\begin{gathered}
\left|q_{0}(t)\right|<M, \quad M=\max \left|q_{0}(t)\right|, \quad\left|K^{n}(t)\right| \leqslant \int_{0}^{t} \frac{t-\tau}{\sqrt{1-(t-\tau)^{2}}}\left|q_{0}(\tau)\right| d \tau<M \\
\left|q_{1}(t)\right| \leqslant \int_{0}^{t}|K(t-\tau)| \cdot\left|q_{0}(\tau)\right| d \tau<M^{2} t, \quad\left|q_{2}(t)\right|<M^{3} \frac{t^{2}}{2!} \\
\left|q_{n}(t)\right|<M^{n+1} \frac{t^{n}}{n!}
\end{gathered}
$$

Then

$$
\left|\sum_{n=0}^{\infty} \varepsilon^{n} q_{n}(t)\right| \leqslant \sum_{n=0}^{\infty} \varepsilon^{n}\left|q_{n}(t)\right|<\sum_{n=0}^{\infty} \varepsilon^{n} M^{n+1} \frac{t^{n}}{n!}=M e^{\varepsilon M t}
$$

Thus, the exact solation of Equation (3.7) with the conditions (3.8) is represented in the form of a series (4.2) which converges uniformly for all values of $t<1$ and any parameter $\epsilon$.

However, for $\epsilon>1$ the solution in the form of the series is inconvenient from practical considerations. We shall derive an approximate solution. For this purpose we shall expand the root $\sqrt{1-t^{2}}$ in a series

$$
\begin{gather*}
\sqrt{1-t^{2}}=\sum_{n=0}^{\infty} a_{n} \cos \gamma_{n} t \quad\left(\gamma_{n}=\frac{2 n+1}{2} \pi\right)  \tag{4.8}\\
\int_{0}^{1} \sqrt{1-t^{2}} \cos \gamma_{n} t d t=\frac{\pi}{2} \frac{J_{1}\left(\gamma_{n}\right)}{\gamma_{n}}=\frac{a_{n}}{2}, \quad \text { or } \quad a_{n}=\pi \frac{J_{1}\left(\gamma_{n}\right)}{\gamma_{n}}
\end{gather*}
$$

where $J_{1}$ is the Bessel function of the first order. One can show that the series (4.8) converges uniformly for all $t$ and rather rapidly at that, since it follows from the properties of Bessel functions that

$$
a_{n} \approx \frac{(-1)^{n} \sqrt{\pi}}{\gamma_{n}} \text { for large } n
$$

We write out several of the first terms of the series (4.8):

$$
\sqrt{1-t^{2}}=1.133 \cos \frac{\pi}{2} t-0.188 \cos \frac{3 \pi}{2} t+0.084 \cos \frac{5 \pi}{2} t-0.050 \cos \frac{7 \pi}{2}+\ldots
$$

In the first approximation we retain only one term of the series, i.e. we let

$$
\begin{equation*}
\sqrt{1-t^{2}} \approx 1.133 \cos \frac{\pi}{2} t \tag{4.9}
\end{equation*}
$$

Substitution of (4.9) into Equation (3.7) yields

$$
\begin{gathered}
L\{q\}=q^{\prime \prime}(t)+2 \alpha q^{\prime}(t)+\beta q(t)-\varepsilon_{1} \int_{0}^{t} \cos \frac{\pi}{2}(t-\tau) q^{\prime}(\tau) d \tau=0 \\
q(0)=0, \quad q^{\prime}(0)=1 \quad\left(\varepsilon_{1}=1.133 \mathrm{e}\right)
\end{gathered}
$$

Let us apply the one-sided Laplace transform and denote by $q^{*}(\lambda)$ the transformation of the function $q(t)$ :

$$
\int_{0}^{\infty} L\{q\} e^{-\lambda t} d t=\left(\lambda^{2}+2 \alpha \lambda+\beta-\varepsilon \frac{\lambda^{2}}{\lambda^{2}++^{1 / 6} \pi^{2}}\right) q^{*}(\lambda)-1=0
$$

From this

$$
\begin{gather*}
q^{*}(\lambda)=\frac{\varphi(\lambda)}{\varphi(\lambda)} . \quad \psi(\lambda)=\lambda^{2}+\frac{1}{4} \pi^{2} \\
\varphi(\lambda)=\lambda^{4}+2 a \lambda^{3}+\left(\frac{1}{4} \pi^{2}+\beta-\varepsilon\right) \lambda^{2}+ \\
+\frac{1}{2} \pi^{2} \alpha \lambda+\frac{1}{4} \pi^{2} \beta \tag{4.10}
\end{gather*}
$$

In order to find the inverse transform $q(t)$ it is necessary to know the roots of the function $\phi(\lambda)$. Let us study the roots of the equation $\phi(\lambda)=0$ by replacing it by its equivalents

$$
y_{1}(\lambda)=y_{2}(\lambda), \quad y_{1}(\lambda)=\lambda^{2}+2 \alpha \lambda+\beta-\varepsilon, \quad y_{2}(\lambda)=-\frac{\pi^{2}}{4} \frac{\varepsilon_{1}}{\lambda^{2}+1 / 4 \pi^{2}}
$$

The real roots of the equation are those values of $\lambda$ for which the curves of the functions $y_{1}(\lambda)$ and $y_{2}(\lambda)$ intersect each other (Fig. 2).

Two cases are possible. If

$$
2 \alpha^{2} \geqslant \beta-\varepsilon_{1}+\sqrt{\left(\beta-\varepsilon_{1}\right)^{2}+\frac{1}{2} \pi^{2}\left(\beta+\varepsilon_{1}\right)+\frac{1}{16} \pi^{4}}-\frac{1}{2} \pi^{2}
$$

then there exist two real negative and two complex roots, whose real parts are positive, according to the Hurwitz criterion. If

$$
2 \alpha^{2}<\beta-\varepsilon_{1}+\sqrt{\left(\beta-\varepsilon_{1}\right)+\frac{1}{2} \pi^{2}\left(\beta+\varepsilon_{1}\right)+\frac{1}{16} \pi^{4}}-\frac{1}{4} \pi^{2}
$$

then all four roots are complex conjugate. The conditions were derived from the inequality $y_{1}(-a)<y_{2}(-a)$. The inverse Laplace transformation will yield the original function

$$
q(t)-\frac{\psi\left(\lambda_{1}\right)}{\varphi^{\prime}\left(\lambda_{1}\right)} e^{\lambda_{1} t}+\frac{\psi\left(\lambda_{2}\right)}{\varphi^{\prime}\left(\lambda_{2}\right)} e^{\lambda_{2} t}+\frac{\psi\left(\lambda_{3}\right)}{\varphi^{\prime}\left(\lambda_{3}\right)} e^{\lambda_{3} t}+\frac{\psi\left(\lambda_{4}\right)}{\varphi^{\prime}\left(\lambda_{4}\right)} e^{\lambda_{4} t}
$$

where $\lambda_{1}, \lambda_{2}, \lambda_{3}$, and $\lambda_{4}$ are the roots of function (4.10). The replacement of the kernel by (4.9) is equivalent to neglecting in the solution harmonics with a high frequency and small amplitude.

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